Content-Preserving Warps for 3D Video Stabilization

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Images courtesy Peter Sand and Flickr user Charles W. Brown

Amateur Video



Traditional 2D Video Stabilization



Our Result



Goal



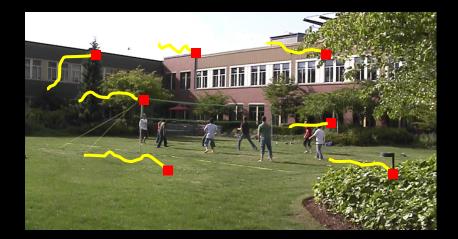


Our result

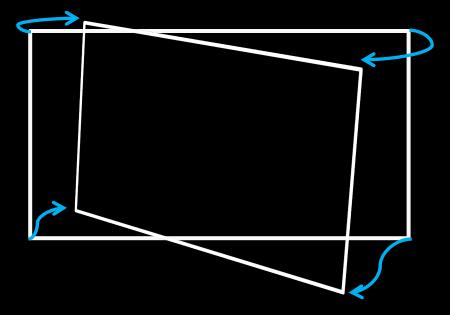
Related Work

Traditional 2D Video Stabilization

Motion estimation



Fit full-frame warps



Limitations

 No knowledge of actual 3D camera path, so cannot control desired motion directly

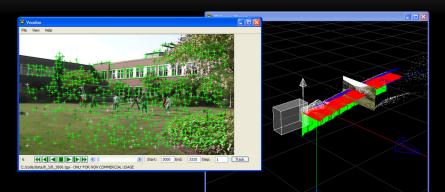
Homography cannot model parallax in 3D scene

3D Video Stabilization

- Non-metric image-based rendering for video stabilization [Buehler et al. 01]
- Image-based rendering using image-based priors [Fitzgibbon et al. 05]
- Using photographs to enhance videos of a static scene [Bhat et al. 07]

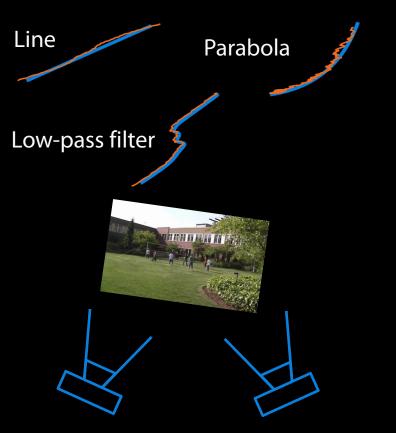
3D Video Stabilization: Pipeline





Camera path planning

Novel view synthesis



IBR based 3D Video Stabilization

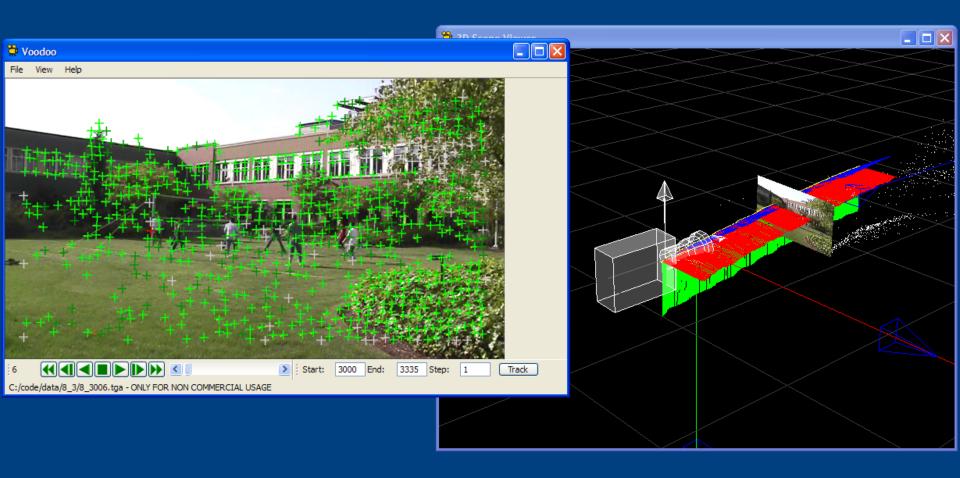


Unstructured lumigraph rendering [Buehler et al. 01]

Our Approach

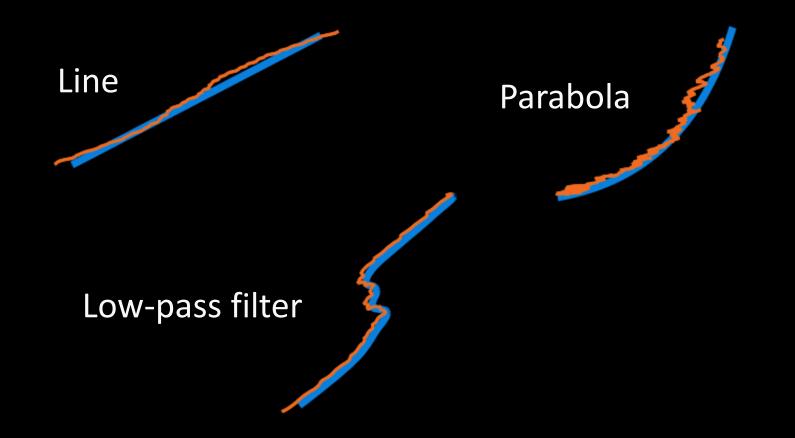
3D Video Stabilization

structure from motion

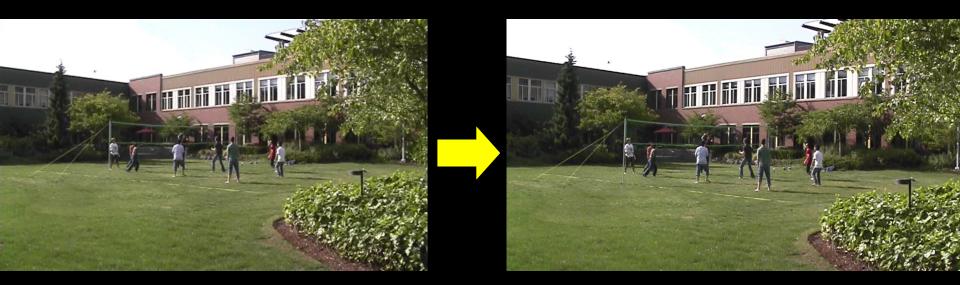


Voodoo Camera Tracker (http://www.digilab.uni-hannover.de)

3D Video Stabilization camera path planning



Temporal Constraint



One input frame

One output frame

Novel View from One Frame

- A Series of Vision Challenges!
 - Segment out layers
 - Determine depth
 - Shift and re-composite layers
 - Fill holes
- Cannot achieve accurate dis-occlusions, nonlambertian reflection, etc

Can We Fake It?

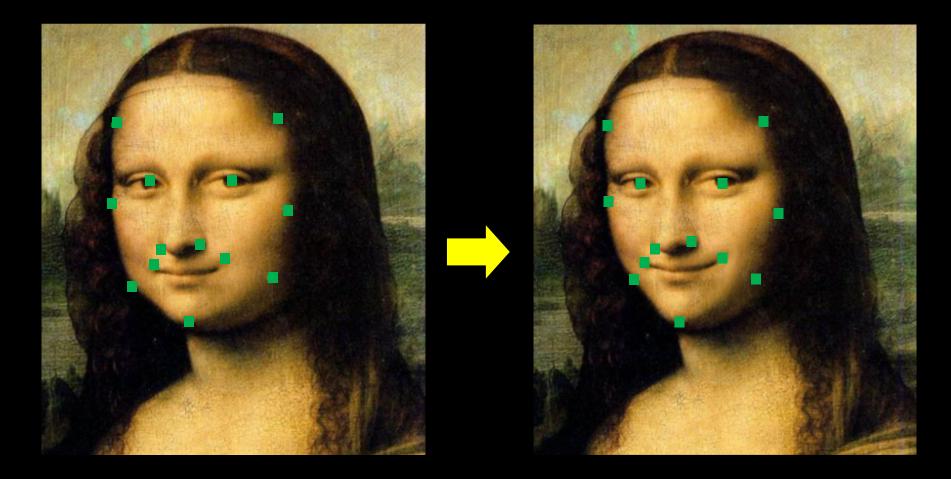
- Viewpoint shifts will be small
- Aim for perceptual plausibility rather than accurate novel view synthesis
 - Salient content move along stabilized paths
 - No noticeable artifacts

Inspirations

- As-rigid-as possible deformation
 - [Igarashi et al. 05, Schaeffer et al. 06, Gal et al. 06]

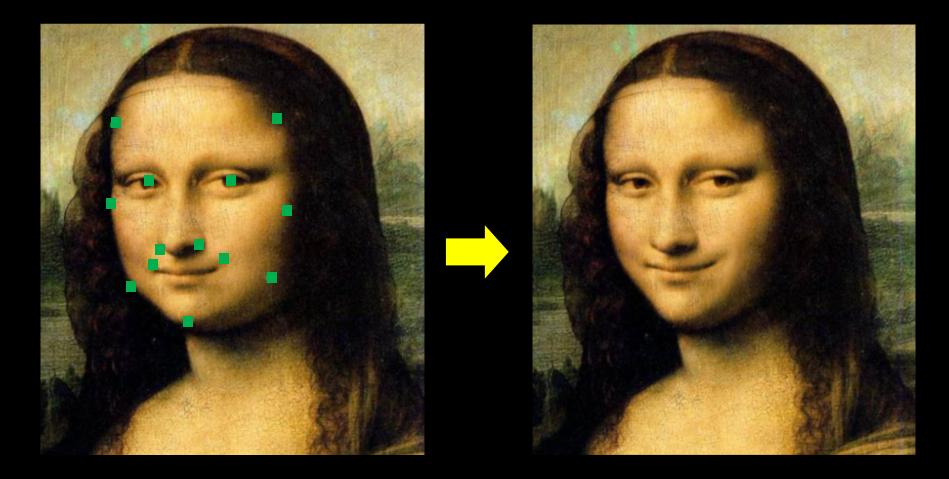
- Image retargeting
 - [Wolf et al. 07, Avidan et al. 07, Wang et al. 08]

As Rigid As Possible Deformation



[Schaeffer et al. 06]

As Rigid As Possible Deformation



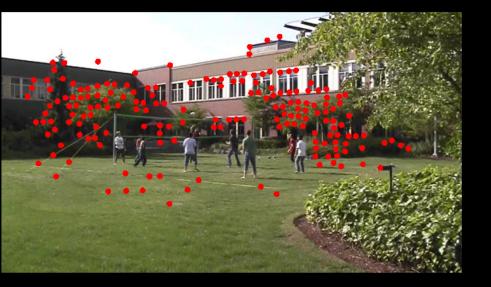
[Schaeffer et al. 06]

Image Retargeting



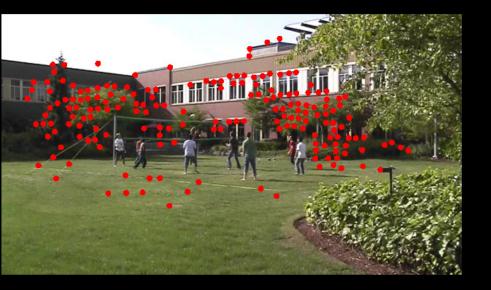
[Avidan et al. 07]

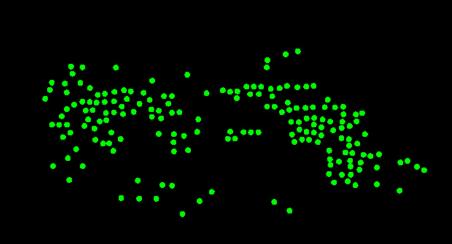
Problem Setup



input frame and points

Problem Setup

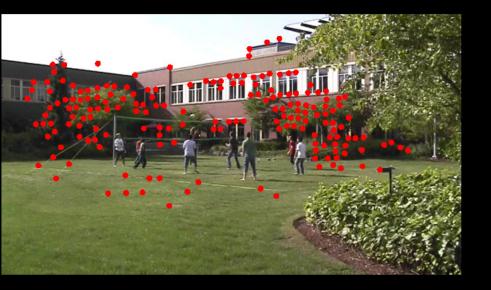




input frame and points

output points

Problem Setup





input frame and points

output frame

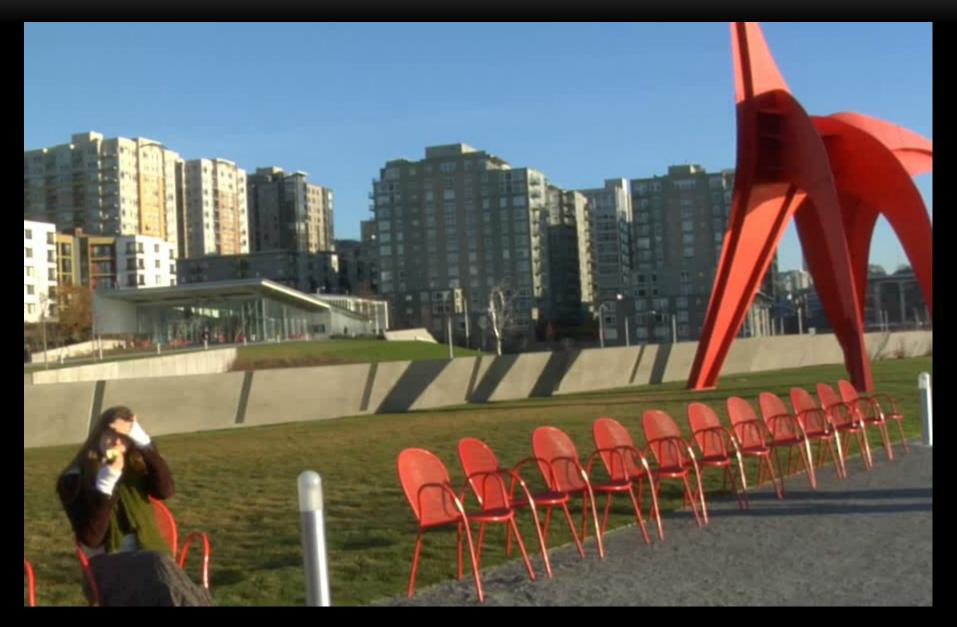
Option 1: Scattered Data Interpolation



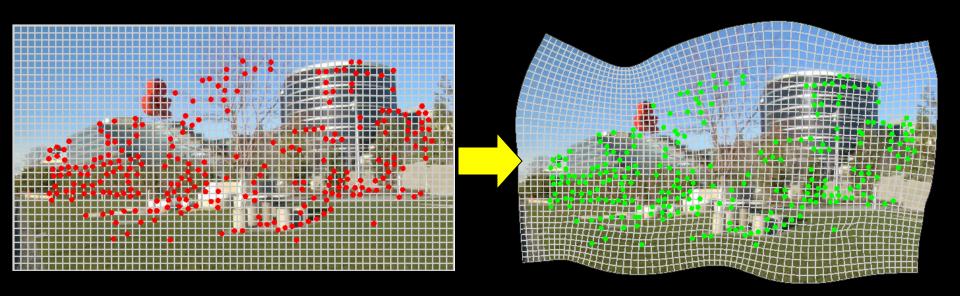
Option 2: Full-frame Warping with Homography



A Less Successful Result



Our Approach

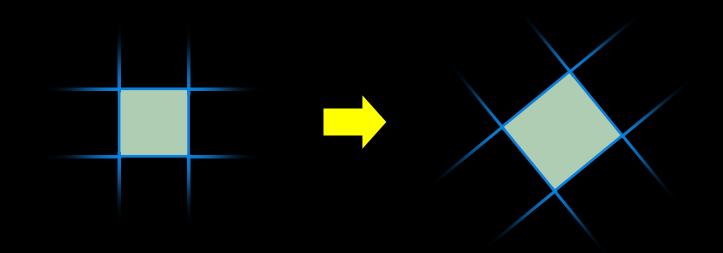


Warp each input frame to create the output frame by least-squares minimization

- Data term: Soft, sparse displacement constraint
- Smoothness term: Local similarity transformation constraint

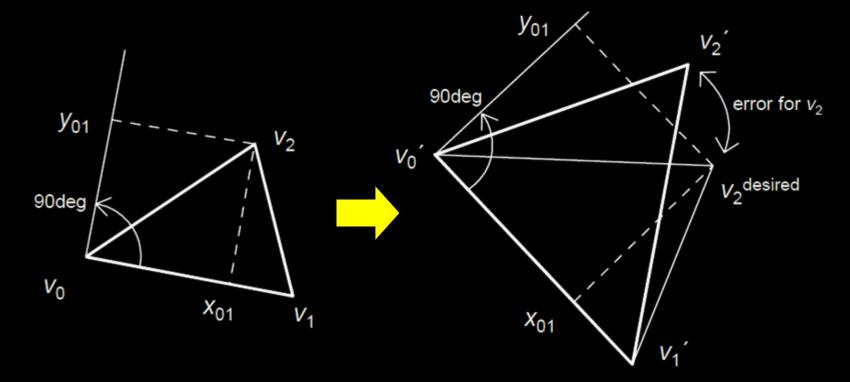
Smoothness Term: Minimize Visual Distortion

Local similarity transformation constraint



Smoothness Term: Minimize Visual Distortion

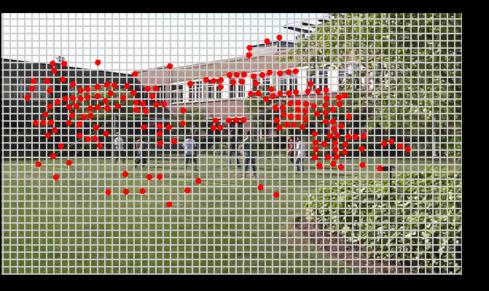
Local similarity transformation constraint



[Igarashi et al. 05]

Saliency Weight

Concentrate distortion to non-salient regions

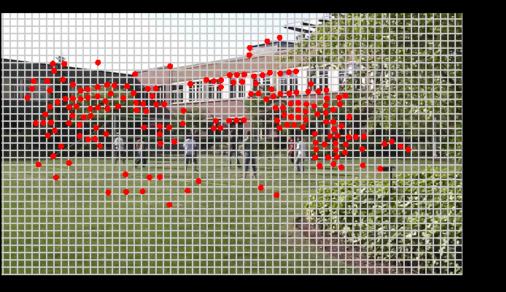


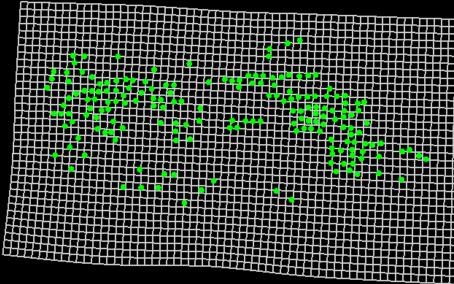


Input

Saliency map

Content-Preserving Warping

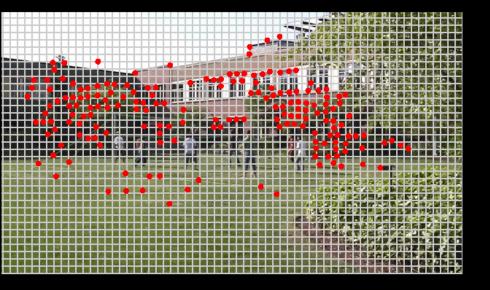




Input

Output

Content-Preserving Warping

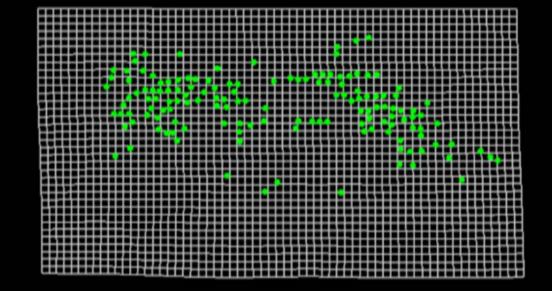




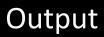
Input

Output

Content-Preserving Warping



Grid mesh & points





More Issues

I. Poor distribution of scene points

II. Temporal incoherence from discontinuous scene point tracks

Poor distribution of scene points



Poor distribution of scene points



No feature points





Input frame



Pre-warping



Pre-warping + content-preserving warping

Method:

Pre-warp input using a best-fitting homography

Result:

✓ Regions with sufficient feature points:
 Content-preserving warping dominates

✓ Regions without sufficient feature points:
 Pre-warping gives a good approximation

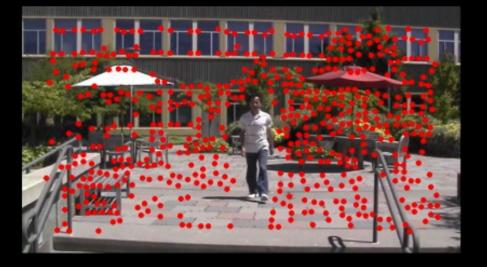


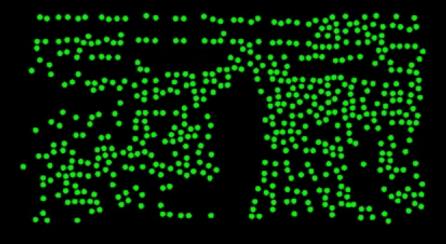
Result of content-preserving warping with pre-warping

More Issues

I. Poor distribution of scene points

II. Temporal incoherence from discontinuous scene point tracks



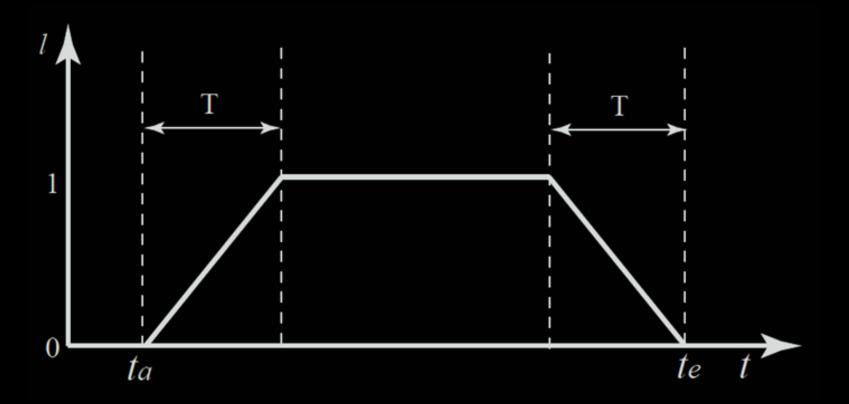


Input video & points

Output points







Fade-in/out the weight of the displacement constraint over time



Result of fade-in/out the weight

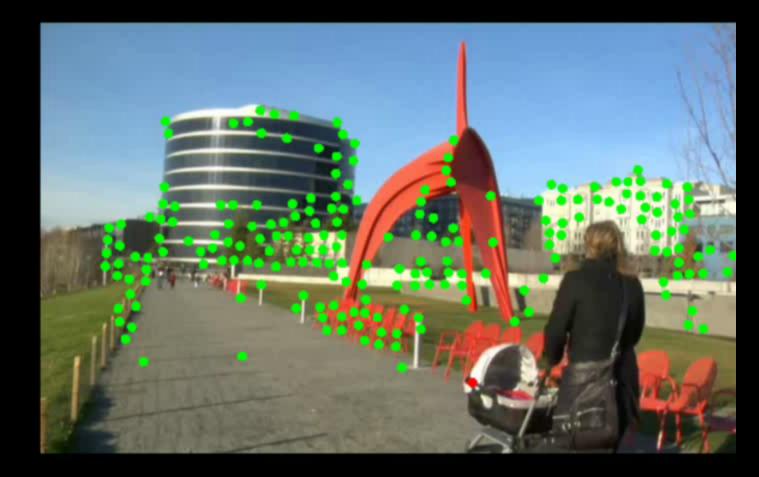
Moving Objects

- No reconstructed 3D points
- Warp follows surrounding background points

- Not correct! But...
 - Viewpoint shifts are small
 - Motion clouds the issue
 - Don't notice exact occlusion relationships



A Contrived Experiment



Camera position

Output points

Novel View Synthesis



Novel View Synthesis



Novel View Synthesis



Evaluation

32 short video clips (5-20 seconds)
 completely successful: 14
 moderately successful: 15
 fail: 3

A Moderately Successful Example



Results & Comparisons

INPUT



Our Output



Results & Comparisons

INPUT



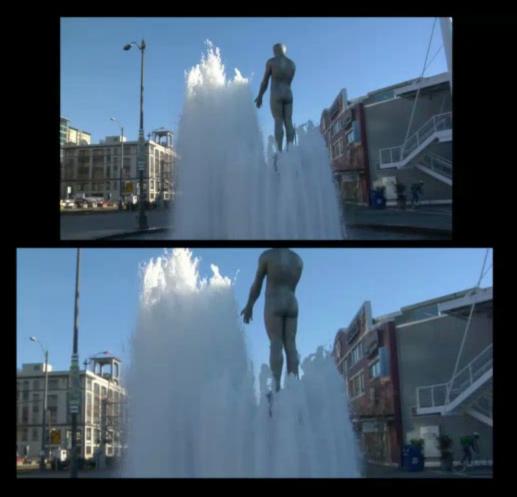
Our Output



Results & Comparisons

INPUT

Our Output



Limitations

- Requires running Structure-from-Motion
 - Slow & memory-intensive
 - More brittle than simple point tracking
 - Requires static regions to lock onto
- Sensitive to poor distribution of recovered scene points
- Aggressive stabilization leads to aggressive cropping

Conclusion

- A technique for simulating the appearance of an idealized camera motion
- Key insight
 - Content-preserving warps can fake small viewpoint shifts
 - Human vision surprisingly tolerant

Thank you

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