CS-322 Target Generation, Part 1


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## Output to Assembly Code (vs. machine code)

Breaks code generation task into 2 phases

- Compiler back-end
- Assembler

Easier to debug compiler output!
Slightly slower (?)

## Porting the Compiler?

Porting to a new target machine architecture.
Re-write the back-end


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## Porting the Compiler?

Porting to a new target machine architecture.
Re-write the back-end


Specification-Driven Approaches
"Code Generator-Generators"
Intermediate Code


## Requirements

- Target code must be correct.
- Target code should be efficient.
- Back-end should run quickly.

Want optimal code sequences?
NP-Complete
Generate all correct code sequences ... and see which is best

## Optimal?

The target program...
... executes faster
... takes less memory
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|  | Code Generation Algorithms <br> Algorithm \#1 <br> Easiest; We'll use for PCAT |
| :--- | :--- |
| Algorithm \#2 |  |
| Algorithm \#3 | $\leftarrow$ Most complex |

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## Code Generation Algorithms

## Algorithm \#1

Algorithm \#2
Algorithm \#3
$\leftarrow$ Most complex

## Example Target Machine

2-Address Architecture

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## Code Generation Algorithm \#1

Statement-by-statement generation
Code for each IR instruction is
generated independently of all other IR instructions.
IR Code:
$\mathrm{a}:=\mathrm{b}+\mathrm{c}$
d $:=a+e$

## Code Generation Algorithm \#1

Statement-by-statement generation Code for each IR instruction is
generated independently of all other IR instructions.
IR Code:
$\mathrm{a}:=\mathrm{b}+\mathrm{c}$
$\mathrm{d}:=\mathrm{a}+\mathrm{e}$

Target Code:

| mov |  | a |
| :---: | :---: | :---: |
| add | c, r0 |  |
| mov | r0, a |  |
| mov | a,r0 |  |
| add | e, ro | d |
| mov | r0, d |  |

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## Code Generation Algorithm \#1

Statement-by-statement generation
Code for each IR instruction is
generated independently of all other IR instructions.
IR Code:
$\mathrm{a}:=\mathrm{b}+\mathrm{c}$
$\mathrm{d}:=\mathrm{a}+\mathrm{e}$

Target Code:


## Code Generation Algorithm \#1

Statement-by-statement generation Code for each IR instruction is generated independently of all other IR instructions.

IR Code:
$\mathrm{a}:=\mathrm{b}+\mathrm{c}$
$\mathrm{d}:=\mathrm{a}+\mathrm{e}$

Target Code:

ALSO: Registers are not used effectively.

| mov | b, r0 |  |
| :---: | :---: | :---: |
| add | $\mathrm{c}, \mathrm{r} 0$ | $\mathrm{a}:=\mathrm{b}+\mathrm{c}$ |
| mov | r0,a |  |
| mov | a, r0 |  |
| add | e, r0 | $\mathrm{d}:=\mathrm{a}+\mathrm{e}$ |
| mov | r0,d |  |

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|  |  | Mac |
| :---: | :---: | :---: |
| IR Code: | x : $=$ | $x+5$ |
| Target Code: | mov | x,r0 |
|  | add | 5, r0 |
|  | mov | r0, x |
| IR Code: | x : $=$ | $x+1$ |
| Target Code: | mov | $\mathrm{x}, \mathrm{r} 0$ |
|  | add | 1, r0 |
|  | mov | r0, x |
| $\underline{\text { Target Code: }}$ | mov | $\mathbf{x}, \mathbf{r} 0$ |
|  | inc | r0 |
|  | mov | r0, x |
| Target Code: | inc | x |

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## Using Registers

Goal: Keep some variables in registers (instead of in memory)
Problem: Not enough registers!

## Register Allocation Problem

Which variables will reside in registers?
[ ... at a given point in the program.]

## Register Assignment Problem

Which register will we use for a variable?
[ For a given variable, we may use a different register at different points in the program.]

## Assume

Multiply Instruction
mul $\mathrm{y}, \mathrm{r} 4<$ Must specify an even numbered register

$$
r 5 \times y \rightarrow[r 4, r 5]
$$

Multiply Instruction
div $\quad \mathrm{y}, \mathrm{r} 4 \longleftarrow$ Must specify an even numbered register

$$
[\mathrm{r} 4, \mathrm{r} 5] \div \mathrm{y} \Rightarrow[\mathrm{r} 4, \mathrm{r} 5]
$$

SRDA: Shift Right Double Arithmetic
srda 32,r6

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```
IR Code:
    \(t:=a+b\)
    \(\mathrm{t}:=\mathrm{t}\) * c
    \(\mathrm{t}:=\mathrm{t} / \mathrm{d}\)
Target Code:
    mov a,r1
    add b,r1
    mul \(c, r 0\)
    div d,r0
    mov \(r 1, t\)
```

| $\frac{\text { IR Code: }}{}$ |  |
| ---: | :--- |
| t | $:=\mathrm{a}+\mathrm{b}$ |
| t | $:=\mathrm{t} * \mathrm{c}$ |
| t | $:=\mathrm{t} / \mathrm{d}$ |
| Target Code: |  |
| mov | $\mathrm{a}, \mathrm{r} 1$ |
| add | $\mathrm{b}, \mathrm{r} 1$ |
| mul | $\mathrm{c}, \mathrm{r} 0$ |
| div | $\mathrm{d}, \mathrm{r} 0$ |
| mov | $\mathrm{r} 1, \mathrm{t}$ |

IR Code:

$$
\begin{aligned}
& \mathrm{t}:=\mathrm{a}+\mathrm{b} \\
& \mathrm{t}:=\mathrm{t}+\mathrm{c} \\
& \mathrm{t}:=\mathrm{t} / \mathrm{d}
\end{aligned}
$$

Target Code:

| mov | $a, r 0$ |
| :--- | :--- |
| add | $b, r 0$ |
| add | $\mathrm{c}, \mathrm{r} 0$ |
| srda | $32, r 0$ |
| div | $d, r 0$ |
| mov | $\mathrm{r} 1, \mathrm{t}$ |

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| IR Code: |  |
| :---: | :---: |
| $\begin{aligned} & \mathrm{t} \\ & \mathrm{t} \\ & \mathrm{t} \\ & \mathrm{l} \\ & \mathrm{t}\end{aligned}=$ | $a+b$ $t * c$ |
| Target Code: |  |
| mov | a, r1 |
| add | b, r1 |
| mul | c, r0 |
| div | d,ro |
| mov | r1,t |

Conclusion:

IR Code:
$\mathrm{t}:=\mathrm{a}+\mathrm{b}$
$\mathrm{t}:=\mathrm{t}+\mathrm{c}$
$\mathrm{t}:=\mathrm{t} / \mathrm{d}$

Target Code:
mov a,r0
add $b, r 0$
add $c, r 0$
srda $32, r 0$
div d,r0
mov $r 1, t$

Where you put the result of $t:=a+b$ (either r0 or r1) depends on how it will be used later!!!
[A "chicken-and-egg" problem]

## Evaluation Order

The IR code establishes an order on the operations.

## Simplest Approach

- Don't mess with re-ordering.
- Target code will perform all operations
in the same order as the IR code


## Trickier Approach

- Consider re-ordering operations
- May produce better code
... Get operands into registers
just before they are needed
... May use registers more efficiently
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## Moving Results Back to Memory

When to move results from registers back into memory?
After an operation, the result will be in a register.

## Immediately

Move data back to memory just after it is computed.
May make more registers available for use elsewhere.
Wait as long as possible before moving it back.
Only move data back to memory "at the end" or "when absolutely necessary"
May be able to avoid re-loading it later!


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## Evaluating A Potential Code Sequence

Each instruction has a "cost"
Cost $=$ Execution Time

Execution Time is difficult to predict.
Pipelining, Branches, Delay Slots, etc.
Goal: Approximate the real cost
A "Cost Model"

## Evaluating A Potential Code Sequence

Each instruction has a "cost"
Cost $=$ Execution Time
Execution Time is difficult to predict.
Pipelining, Branches, Delay Slots, etc.
Goal: Approximate the real cost

## A "Cost Model"

Simplest Cost Model:
Code Length $\approx$ Execution Time Just count the instructions!
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## A Better Cost Model

Look at each instruction.
Compute a cost (in "units").
Count the number of memory accesses.
Cost $=1+$ Cost-of-operand-1 + Cost-of-operand-2 + Cost-of-result

|  | example |  | $\frac{\text { cost }}{1}$ |
| ---: | :--- | :--- | :--- |
| Absolute Memory Address | $\mathbf{x}$ |  | 0 |
| Register | $r 0$ | 0 |  |
| Literal | 39 | 0 | 0 |
| Indirect Register | $[r 1]$ | 1 |  |
| Indirect plus Index | $[r 1+48]$ | 1 |  |
| Double Indirect | $[[r 1+48]]$ | 2 |  |

Example: sub 97,r5 r5-97 $\rightarrow$ r5
Cost $=1+0+0+0=1$
Example: sub 97,[r5] [r5]-97 $\rightarrow$ [r5]
Cost $=1+1+0+1=3$
Example: sub [r1],[[r5+48]] [[r5+48]]-[r1] $\rightarrow[[r 5+48]]$ Cost $=1+2+1+2=6$

## Code Generation Example

IR Code: $\mathrm{x}:=\mathrm{y}+\mathrm{z}$
Translation \#1: $\left.\begin{array}{ccc}\operatorname{mov} \\ \operatorname{add}, x & 3 \\ \mathbf{z}, \mathbf{x}\end{array}\right\} \operatorname{Cost}=7$
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## Code Generation Example

IR Code: $x:=y+z$
Translation \#1: $\left.\begin{array}{ccc}\operatorname{mov} & \mathbf{y}, \mathbf{x} & 3 \\ \text { add } & \mathbf{z}, \mathbf{x} & 4\end{array}\right\}$ Cost $=7$
Translation \#2: mov $\left.\begin{array}{llll}\mathrm{y}, \mathrm{r} 1 & 2 \\ \text { add } & \mathrm{z}, \mathrm{r} 1 & 2\end{array}\right\}$ Cost $=6 \quad \frac{\text { Lesson \#1: }}{\text { Use Registers }}$

## Code Generation Example

IR Code: $\mathrm{x}:=\mathrm{y}+\mathrm{z}$
Translation \#1: $\left.\begin{array}{ccc}\operatorname{mov} & \mathbf{y , x} & 3 \\ \operatorname{add} & \mathbf{z , x} & 4\end{array}\right\}$ Cost =7
Translation \#2:
$\left.\begin{array}{lll}\operatorname{mov} & \mathbf{y}, \mathbf{r} 1 & 2 \\ \operatorname{add} & \mathbf{z}, \mathbf{r} 1 & 2 \\ \operatorname{mov} & \mathbf{r}, \mathbf{x} & 2\end{array}\right\}$ Cost $=$

Lesson \#1:
Use Registers

Translation \#3:
Assume " $y$ " is in $r 1$ and " $z$ " is in r2
Lesson \#2:

Assume " $y$ " will not be needed again

$$
\left.\begin{array}{lll}
\operatorname{add} & r 2, r 1 & 1 \\
\operatorname{mov} & r 1, x & 2
\end{array}\right\} \operatorname{Cost}=3
$$

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## Code Generation Example

IR Code: $x:=y+z$
$\left.\begin{array}{llll}\text { Translation \#1: } & \begin{array}{c}\text { mov } \\ \text { add }\end{array} \quad \begin{array}{l}\mathbf{z}, \mathbf{x}\end{array} & 4\end{array}\right\}$ Cost $=7$
Translation \#2: mov $\left.\begin{array}{lll}\mathrm{y}, \mathrm{r} 1 & 2 \\ \text { add } & \mathrm{z}, \mathrm{r} 1 & 2 \\ \text { mov }\end{array}\right\}$ Cost $=6 \quad \begin{aligned} & \text { Lesson \#1: } \\ & \text { Use Registers }\end{aligned}$
Translation \#3:
Assume " $y$ " is in $r 1$ and " $z$ " is in $r 2$
Lesson \#2:

Assume " $y$ " will not be needed again

$$
\left.\begin{array}{lll}
\text { add } & r 2, r 1 & 1 \\
\text { mov } & r 1, x & 2
\end{array}\right\} \operatorname{Cost}=3 \frac{\text { Lesson \#3: }}{\text { Avoid or delay storing }}
$$

Translation \#4: into memory.
Assume " $y$ " is in $r 1$ and " $z$ " is in $r 2$
Assume " $y$ " will not be needed again.
Assume we can keep " $x$ " in a register.

$$
\text { add } \quad \mathrm{r} 2, \mathrm{rl} 1 \quad 1\} \operatorname{Cost}=1
$$

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## Code Generation Example

IR Code: $\mathrm{x}:=\mathrm{y}+\mathrm{z}$
Translation \#1: $\left.\begin{array}{ccc}\text { mov } \\ \text { add }\end{array} \begin{array}{ll}\mathbf{y}, \mathbf{x} & 3 \\ \mathbf{z}, \mathbf{x}\end{array}\right\} \operatorname{Cost}=7$
$\left.\begin{array}{llll}\text { Translation \#2: } & \operatorname{mov} & \mathrm{y}, \mathrm{r} 1 & 2 \\ \operatorname{add} & \mathrm{z}, \mathrm{r} 1 & 2\end{array}\right\}$ Cost $=6 \quad \begin{aligned} & \text { Lesson \#1: } \\ & \text { Use Registers }\end{aligned}$

Translation \#3:
Assume " $y$ " is in $r 1$ and " $z$ " is in r2
Lesson \#2:

Assume " $y$ " will not be needed again $\left.\begin{array}{lll}\text { add } & \mathrm{r} 2, \mathrm{r} 1 & 1 \\ \mathrm{mov} & \mathrm{r}, \mathrm{x} & 2\end{array}\right\} \operatorname{Cost}=3 \frac{\text { Lesson \#3: }}{\text { Avoid or delay storing }}$
Translation \#4:
$\left.\begin{array}{rl}\mathrm{r} 1, \mathrm{x} & 2\end{array}\right\} \operatorname{Cost}=3 \begin{array}{r}\text { Avoid or delay storing } \\ \text { into memory. }\end{array}$
Assume " $y$ " is in $r 1$ and " $z$ " is in $r 2$
Assume " $y$ " will not be needed again.
Assume we can keep " $x$ " in a register. $\left.\begin{array}{l}\text { keep " } x \text { " in a register. } \\ \text { add } \\ \mathrm{r} 2, \mathrm{r} 1\end{array}\right] \operatorname{Cost}=1 \quad \begin{aligned} & \text { Use different addr } \\ & \text { modes effectively. }\end{aligned}$
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Keep variables in registers
add $\mathrm{r} 2, \mathrm{r} 1 \quad 1\}$ Cost $=1$ Use different addressing
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## Basic Blocks

Break IR code into blocks such that...
The block contains NO transfer-of-control instructions ... except as the last instruction

- A sequence of consecutive statements.
- Control enters only at the beginning.
- Control leaves only at the end.


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|  | Basic Blocks |  |
| :---: | :---: | :---: |
| Label_43: | $\begin{aligned} & \text { t3 }:=t 4+7 \\ & \text { t5 }:=\mathrm{t} 3-8 \\ & \text { if } \mathrm{t} 5<9 \text { goto Label_44 } \end{aligned}$ | $\mathbf{B}_{1}$ |
|  | $\text { t6 }:=1$ <br> goto Label 45 | $\mathbf{B}_{2}$ |
| Label_44: | t6 : = 0 | $\overline{B_{3}}$ |
| Label_45: | $\begin{aligned} \mathrm{t} 7 & :=\mathrm{t} 6+3 \\ \mathrm{t} 8 & :=\mathrm{y}+\mathrm{z} \\ \mathrm{x} & :=\mathrm{t} 8-4 \\ \mathrm{y} & :=\mathrm{t} 8+\mathrm{x} \end{aligned}$ | $\mathbf{B}_{4}$ |
| Label_46: | $\begin{aligned} & z:=w+x \\ & \text { t9 }:=z-5 \end{aligned}$ | $\mathbf{B}_{5}$ |

## Control Flow Graph


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## Algorithm to Partition Instructions into Basic Blocks

Concept: "Leader"
The first instruction in a basic block
Idea:
Identify "leaders"

- The first instruction of each routine is a leader.
- Any statement that is the target of a branch / goto is a leader.
- Any statement that immediately follows
a branch / goto a call instruction
... is a leader

A Basic Block consists of
A leader and all statements that follow it
... up to, but not including, the next leader


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## Use (B) <br> Look at Each Basic Block in Isolation

The set of variables used (i.e., read) by the Basic Block
(... before being written / updated)

The "inputs" to the BB
Def (B)
The set of variables in the Basic Block that are written / assigned to.
The "outputs" of the BB
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## Use (B) <br> Look at Each Basic Block in Isolation

The set of variables used (i.e., read) by the Basic Block
(... before being written / updated)

The "inputs" to the BB
Def (B)
The set of variables in the Basic Block that are written / assigned to.
The "outputs" of the BB

$$
\begin{aligned}
& \text { Use }\left(B_{7}\right)=y, v, w \\
& \text { Def }\left(B_{7}\right)=\text { ? }
\end{aligned}
$$

## Use (B) <br> Look at Each Basic Block in Isolation

The set of variables used (i.e., read) by the Basic Block
(... before being written / updated)

The "inputs" to the BB
Def (B)
The set of variables in the Basic Block that are written / assigned to.
The "outputs" of the BB

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Use (B)
Look at Each Basic Block in Isolation
The set of variables used (i.e., read) by the Basic Block
(... before being written / updated)

The "inputs" to the BB
Def (B)
The set of variables in the Basic Block that are written / assigned to.
The "outputs" of the BB

> Use $\left(B_{7}\right)=y, v, w$
> $\operatorname{Def}\left(B_{7}\right)=\mathbf{x}, \mathbf{z}, v$

View the basic block as a function

$$
\begin{aligned}
&<\mathrm{x}, \mathrm{z}, \mathrm{v}>:=\mathrm{f}(\mathrm{y}, \mathrm{v}, \mathrm{w}) \\
& \text { Okay to transform the block! } \\
& \text { (as long as it computes the same function) }
\end{aligned}
$$

## Common Sub-Expression Elimination

A Basic Block:


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## Common Sub-Expression Elimination

Transform:


Into:

$$
\begin{aligned}
& \mathrm{x}:=\mathrm{b}+\mathrm{c} \\
& \mathrm{y}:=\mathrm{a}-\mathrm{d} \\
& \mathrm{~d}:=\mathrm{x}
\end{aligned}
$$

## Common Sub-Expression Elimination

Transform:

```
x := b + c
y := a - d
d := b + c
z := a - d
```

$\qquad$

``` What about "and"... z := a - d Do we need to recompute?
```

Into:

$$
\begin{aligned}
& \mathrm{x}:=\mathrm{b}+\mathrm{c} \\
& \mathrm{y}:=\mathrm{a}-\mathrm{d} \\
& \mathrm{~d}:=\mathrm{x} \\
& \mathrm{z}:=\text { ????? }
\end{aligned}
$$

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## Common Sub-Expression Elimination

Transform:


Into:
$\mathrm{x}:=\mathrm{b}+\mathrm{c}$
$\mathrm{y}:=\mathrm{a}-\mathrm{d}$
d := x Yes!
$z:=a-d \quad$ "d" has been changed since "a-d" computed!
Now, "add" may compute a different value!

## Reordering Instructions in a Basic Block

Sometimes we can change the order of instructions...


## Reordering Instructions in a Basic Block

Sometimes we can change the order of instructions...


But some changes would change the program!

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## Reordering Instructions in a Basic Block

Sometimes we can change the order of instructions...

But some changes would change the program!
Not Okay!
When can we exchange these two instructions?

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## Reordering Instructions in a Basic Block

Sometimes we can change the order of instructions...


But some changes would change the program!
When can we exchange these two instructions?

$$
\begin{aligned}
& \mathbf{x}:=\cdots \cdot v_{1} \cdots v_{2} \cdots \\
& \mathbf{y}:=\cdots v_{3} \cdots v_{4} \cdots
\end{aligned}
$$

If and only if...

$$
\begin{aligned}
v_{1} \not \neq y \\
v_{2} \neq y \\
v_{3} \neq x \\
v_{4} \neq x
\end{aligned}
$$

Any variables (including possibly " $x$ " and " $y$ ')
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> "Is some variable $\frac{\text { Live Variables }}{\text { x live at some point } P \text { in the }}$ program?"

Could the value of " $x$ " at point $P$ ever be needed later in the execution?

## Live Variables

"Is some variable $x$ live at some point $P$ in the program?"

Could the value of " $x$ " at point $P$ ever be needed later in the execution?
"Point in a program"
A point in a program occurs between two statements.
$a:=b+c \longleftarrow$ Point P
$d:=e * f \longleftarrow$
c : $=\mathrm{b}-5$ $\qquad$
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$\square$
Live Variables
"Is some variable $x$ live at some point $P$ in the program?"

Could the value of " $x$ " at point $P$ ever be needed later in the execution?
"Point in a program"
A point in a program occurs between two statements.
$\mathrm{a}:=\mathrm{b}+\mathrm{c} \longleftarrow$ Point $\mathbf{P}$
d :=e * f
c : $=\mathrm{b}-5$ $\qquad$

Is it possible that the program will ever read from $x$ along a path from $P$ ?
[... before " $x$ " is written / stored into]
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## "Dead" Variables

A Variable is "Dead at point $P$ "
$=$ Not Live

Value will definitely never be used.
No need to compute it!
If value is in register, no need to store it!

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## Liveness Example


$\qquad$

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## Liveness Example



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## Liveness Example

Must look at the whole "control flow graph" to determine liveness.

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## Liveness Example

Must look at the whole "control flow graph" to determine liveness.


## Liveness Example

Must look at the whole "control flow graph" to determine liveness.

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## Liveness Example

Must look at the whole "control flow graph" to determine liveness.


## Liveness Example

Must look at the whole "control flow graph" to determine liveness.


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## Live Variable Analysis

A Rather Complex Algorithm

## Input:

The Control Flow Graph
$\left.\underset{\underset{i}{\operatorname{Use}\left(B_{i}\right)}}{\operatorname{Def}\left(B_{i}\right)}\right\}$ for all $B_{i}$
Output:
Live $\left(B_{i}\right)=$ a list of all variables live at the end of $B_{i}$
Live Variable Analysis missing?
Assume all variables are live at the end of each basic block.

## Temporaries

Assumption:
Each temporary is used in only one basic block (True of temps for expression evaluation)


## Conclusion:

Temps are never live at the end of a basic block.

If Live-Variable-Analysis is missing...
this assumption can at least identify many dead variables.
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## Dead Code

"Dead Code" (first meaning)
Any code that cannot be reached.
(Will never be executed.)

$$
x:=y+z
$$

$$
\text { goto Label } 45
$$

---
Label_45: z := x - a

## Dead Code

## "Dead Code" (first meaning)

Any code that cannot be reached.
(Will never be executed.)

```
            \(\mathbf{x}:=\mathrm{y}+\mathrm{z}\)
                goto Label 45
---- \(\frac{a}{a}: \equiv \bar{b}^{-} \mp{ }^{-}{ }^{-}=---1\) Dead Code (unreachable)
```



```
    Label 45:
                z := x - a
```

"Dead Code" (second meaning)
A statement which computes a dead variable.
Example:

$$
\begin{aligned}
& \mathrm{b}:=\mathrm{x} * \mathrm{y} \\
& \mathrm{a}:=\mathrm{b}+\mathrm{c} \longleftarrow \text { If "6" } \mathrm{a} \text { is not live here... } \\
& \cdots \\
& \text { Then eliminate this statement!!!! }
\end{aligned}
$$

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## Temporaries

If you can identify a variable which is not in $\operatorname{Use}\left(\mathbf{B}_{\mathbf{i}}\right)$ for any basic block
(e.g., a temporary used only in this basic block)

Then you may...

- Rename the variable
- Keep the variable in a register instead of in memory
- Eliminate it entirely (during some optimization)


## Must be careful that the variable

is not used in other routines
(i.e., accessed as a non-local from another routine)

## Algebraic Transformations

Watch for special cases.
Replace with equivalent instructions
... that execute with a lower cost.

## Examples

$$
\begin{aligned}
& x:=y+0 \quad \Rightarrow \quad x \quad:=y \\
& x:=y \text { * } 1 \Rightarrow x:=y \\
& x \quad:=y \text { ** } 2 \Rightarrow x \quad:=y \text { * } y \\
& x:=y+1 \quad \Rightarrow \quad x:=\operatorname{incr}(y) \\
& x:=y-1 \quad \Rightarrow \quad x \quad:=\operatorname{decr}(y) \\
& \text {...etc... }
\end{aligned}
$$

May do some transformations during "Peephole Optimization."
Other transformations may be Target Architecture Dependent
(use your "cost model" to determine when to transform)
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## Control Flow Graphs

## Definitions:

- Initial Block
- Predecessor Blocks
- Successor Blocks

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## What is a "LOOP"?

A cycle in the flow graph.
Can go from $B$ back to $B$.
A path from B to B.
All blocks on any path from B to B.

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## Natural Loops

Each loop has a unique entry (its "Header Block")
To reach any block in the loop (from outside the loop) you must first go through the header block

Result from "structured programming" constructs while, for, do-until, if, ...

Concepts:
"loop nesting"
"inner / outer loops"


